

# Positive Solutions of Elliptic and Parabolic Problems with Nonlocal Lower Order Terms

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**Abstract** The existence of positive solution about nonlocal boundary problems with lower order nonlocal terms

$$\begin{cases} -a(\int_{\Omega}|u|^q dx)\Delta u + b(l(u))u = f(x, u), & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

and its parabolic counterpart were considered where  $\Omega$  was a bounded smooth domain of  $\mathbf{R}^N$  ( $N > 2$ ),  $a$  and  $b$  were given function. By using Galerkin method, the existence of positive solution for the nonlocal elliptic problems was obtained moreover, the existence of positive solution for the evolution case was proved.

**Key words** non local problem, boundary value problem, positive solution, Galerkin method

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## 具有低阶项的非局部椭圆及抛物问题的正解

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[摘要] 考虑了非局部边值问题

$$\begin{cases} -a(\int_{\Omega}|u|^q dx)\Delta u + b(l(u))u = f(x, u), & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

及其相应的非局部抛物问题的正解存在性. 其中  $\Omega$  是  $\mathbf{R}^N$  中的有界光滑区域,  $a$  和  $b$  是给定的函数. 利用 Galerkin 方法, 首先获得了具有低阶项的非局部椭圆问题正解的存在性, 进一步证明了抛物问题正解的存在性.

[关键词] 非局部问题, 边值问题, 正解, Galerkin方法

In this paper we concerned with the elliptic problems with non local lower order terms

$$\begin{cases} -a(\int_{\Omega}|u|^q dx)\Delta u + b(l(u))u = f(x, u), & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (1)$$

and its parabolic counterpart

$$\begin{cases} u_t - a(\int_{\Omega}|u|^q dx)\Delta u + b(l(u))u = f(x, u), & \text{in } Q_T = \Omega \times (0, T), \\ u(x, t) = 0 & \text{on } \Gamma = \partial\Omega \times (0, T), \\ u(x, 0) = u_0(x) \geqslant 0 & \text{in } \Omega, \end{cases} \quad (2)$$

where  $1 \leqslant q < 2N/(N-2)$ ,  $a: \mathbf{R} \rightarrow (0, \infty)$ ,  $b: \mathbf{R} \rightarrow (0, \infty)$  and  $f: \Omega \times \mathbf{R} \rightarrow (0, \infty)$  are given functions who-

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ses properties will be timely introduced. If  $L^2(\Omega) \rightarrow \mathbf{R}$  is a continuous linear form,  $\Omega$  is a bounded smooth domain of  $\mathbf{R}^N$  ( $N > 2$ ). These problems arise in various physical situation and biological models. For instance when we study question related with a culture of bacteria,  $u$  could describe the population of these bacteria and so  $u > 0$  in  $\Omega$ . Here the diffusion coefficient  $a$  is supposed to depend on the entire population in the domain rather than on the local density and the  $b(l(u))u$  is the density of death or extinction of the population at stake. It's relatively normal to assume this death to be proportional to the density of population by a factor  $b$ . Now this factor could have  $b = b(\int_{\Omega} u(x) dx)$ ,  $b$  depends on the entire population. In the recent years several papers have been devoted to the study of nonlocal elliptic and parabolic problems<sup>[1-7]</sup>. But in this paper, we consider the elliptic and parabolic problems with nonlocal lower order terms, using Galerkin method obtained the positive solution. Throughout this paper we will suppose that

(C<sub>1</sub>)  $a(s)$  is a continuous function and  $0 < m_0 \leq a(s) \leq M$ ,  $\forall s \in \mathbf{R}$ ;

(C<sub>2</sub>)  $b(s)$  is a continuous function and  $0 < \alpha \leq b(s) \leq \beta$ ,  $\forall s \in \mathbf{R}$ ;

(C<sub>3</sub>)  $L^2(\Omega) \rightarrow \mathbf{R}$  is a continuous linear form, there is a  $g(x) \in L^2(\Omega)$  such that  $l(u) = l_g(u) = \int_{\Omega} g(x)u(x) dx$  for all  $u \in L^2(\Omega)$ .

## 1 The Stationary Problem

In this section we are going to consider problem (1) by using a Galerkin method. We can see in [8, 9] about Galerkin method in nonlocal problem. Concerning to problem (1) we will suppose that

(H<sub>1</sub>)  $f: \Omega \times \mathbf{R} \rightarrow (0, \infty)$  is a Carathéodory function and satisfying  $f(x, u) \leq h(x)u(x) + g(x)$ , where  $h(x), g(x) \in C(\Omega)$  and  $h, g > 0$  in  $\Omega$ ,  $a = \max h(x)$ ,  $b = \max g(x)$ .

Under these assumptions, we say a function  $u \in H_0^1(\Omega)$  is called weak solution of problem (1) if for  $\forall \phi \in H_0^1(\Omega)$ ,

$$a(\int_{\Omega} |u|^q dx) \int_{\Omega} u \bar{\phi} dx + b(l(u)) \int_{\Omega} \phi dx - \int_{\Omega} (x, u) \phi dx = 0. \quad (3)$$

**Theorem 1** Let assume that condition (C<sub>1</sub>), (C<sub>2</sub>) and (C<sub>3</sub>) hold. Let assume in addition that (H<sub>1</sub>) and  $m_0 < \frac{a-\alpha}{\lambda_1}$ ,  $a > \alpha$ , where  $\lambda_1$  is the principal eigenvalue of  $-\Delta$  in  $H_0^1(\Omega)$ . Then problem (1) has at least one positive solution.

**Proof** Let  $\{v_k\}_{k=1}^{\infty}$  be a complete orthonormal system for  $H_0^1(\Omega)$  with norm  $\|u\|^2 = \int_{\Omega} |u|^2 dx$ . For each fixed  $n \in \mathbf{N}$ , consider the finite-dimensional Hilbert space  $V_n = \text{span}\{v_1, \dots, v_n\}$ . Then  $V_n$  is isometric to  $\mathbf{R}^n$  for each  $v \in V_n$ , is uniquely associate to  $\xi = (\xi_1, \dots, \xi_n) \in \mathbf{R}^n$  by the relation  $v = \sum_{k=1}^n \xi_k v_k$ . We get  $\|u\| = \|\xi\|_{\mathbf{R}^n}$ . We search for solution  $u_n \in V_n$  of the approximate problem

$$a(\int_{\Omega} |u_n|^q dx) \int_{\Omega} u_n \bar{v}_k dx + b(l(u_n)) \int_{\Omega} u_n v_k dx - \int_{\Omega} (x, u_n) v_k dx = 0 \quad (4)$$

Consider the function  $F_n: \mathbf{R}^n \rightarrow \mathbf{R}^n$  defined by

$$(F_n u)_k = a(\int_{\Omega} |u|^q dx) \int_{\Omega} u \bar{v}_k dx + b(l(u)) \int_{\Omega} u v_k dx - \int_{\Omega} (x, u) v_k dx \quad (5)$$

$\forall u \in V_n$ . By (H<sub>1</sub>), (C<sub>1</sub>) and (C<sub>2</sub>), we can easily get  $F_n$  is continuous and

$$\langle F_n u, u \rangle = a(\int_{\Omega} |u|^q dx) \int_{\Omega} |u|^2 dx + b(l(u)) \int_{\Omega} u^2 dx - \int_{\Omega} (x, u) u dx$$

Using (H<sub>1</sub>), Poincaré and Hölder inequalities, we get

$$\langle F_n u, u \rangle \geq (m_0 - \frac{a-\alpha}{\lambda_1}) \|u\|^2 - b |\Omega|^{\frac{1}{2}} \lambda_1^{-\frac{1}{2}} \|u\|^2 > 0$$

if  $\|u\| = R$ , for  $R$  large enough independently of  $n$ , where  $|\Omega|$  is the Lebesgue measure of the set  $\Omega$ . Thus by using Brouwer fixed point theorem in [10], then (5) has a solution  $u_n \in V_n$  and  $\|u_n\| \leq R$ ,  $\forall n \in \mathbf{N}$ . From the

completeness of  $u_n$ , which implies that

$$a \left( \int_{\Omega} |u_n|^q dx \right) \int_{\Omega} u_n \bar{v} dx + b(l(u_n)) \int_{\Omega} u_n v dx - \int_{\Omega} (x, u_n) v dx = 0, \quad (6)$$

$\forall v \in H_0^1(\Omega)$ , let us prove that the sequence  $\{u_n\} \subset H_0^1(\Omega)$  has a convergent subsequence which converges to a solution of (1). In fact since  $\{u_n\}$  is a bounded there exists a subsequence still denoted by  $\{u_n\}$ , such that

$$\begin{aligned} u_n &\rightarrow u \text{ in } H_0^1(\Omega), \quad u_n \rightarrow u \text{ in } L^2(\Omega), \\ u_n &\rightarrow u \text{ in } L^p(\Omega), \quad 1 \leq p < 2N/(N-2), \quad u_n(x) \rightarrow u(x) \text{ a.e. in } \Omega, \\ \|u_n\|_p^p &\rightarrow \|u\|_p^p, \end{aligned}$$

and by (C<sub>3</sub>), we have that  $l(u_n) \rightarrow l(u)$ . Hence, using above and passing to the limit in (6), it shows that  $u$  is a weak solution of problem (1). Next we prove  $u > 0$ . Set  $u^+ = \max\{u, 0\}$ ,  $u^- = \min\{u, 0\}$ . Then  $u = u^+ + u^-$ . Because  $u$  is a weak solution of (1) and let  $\phi = u^-$  in (3), we can get

$$a \left( \int_{\Omega} |u|^q dx \right) \int_{\Omega} |u^-|^2 dx + b(l(u)) \int_{\Omega} |u^-|^2 dx = \int_{\Omega} (x, u) u^- dx$$

From the assumption we obtain

$$\int_{\Omega} (x, u) u^- dx \geq 0$$

But  $f(x, u) > 0$  and  $u^- \leq 0$  hence  $\int_{\Omega} f(x, u) u^- dx = 0$ . We have

$$u^- = 0 \text{ i.e. } u \geq 0$$

So  $u$  is a positive solution.

## 2 The Parabolic Problem

In this section, we consider the parabolic problem (2). First we give a definition of weak solution below. In which assume satisfies the addition condition

(H<sub>2</sub>)  $f: \Omega \times \mathbf{R} \rightarrow (0, \infty)$  is a Carathodory function and satisfying  $|f(x, u)| \leq c(1 + |u|)$ .

**Definition 1** We say a function  $u \in L^2(0, T; H_0^1(\Omega))$  with  $u' \in L^2(0, T; H^{-1}(\Omega))$  is a weak solution of (2), provided

$$(i) \int_{\Omega} u' v dx + a \left( \int_{\Omega} |u|^q dx \right) \int_{\Omega} u \bar{v} dx + b(l(u)) \int_{\Omega} w dx = \int_{\Omega} (x, u) v dx, \quad (7)$$

for each  $v \in H_0^1(\Omega)$  and a.e. time  $0 \leq t \leq T$ .

$$(ii) u(0) = u_0(x).$$

**Lemma 1** If  $u \in L^2(0, T; H_0^1(\Omega))$  with  $u' \in L^2(0, T; H^{-1}(\Omega))$  is a nontrivial solution of problem (2), then  $u(x, t) > 0$   $x \in \Omega$ ,  $t \geq 0$

**Proof** Multiplying  $u^-$  by Eq (7), and integrating over  $Q_T$ , we can see

$$\begin{aligned} \int_{\Omega} \int_0^T \frac{\partial u}{\partial t} u^- dt dx + a \left( \int_{\Omega} |u|^q dx \right) \int_{\Omega} \int_0^T u \bar{u}^- dt dx + b(l(u)) \int_{\Omega} \int_0^T u u^- dt dx = \\ \int_{\Omega} \int_0^T f(x, u) u^- dt dx. \end{aligned}$$

Considering the above terms respectively because  $u_0(x) > 0$

$$\begin{aligned} \int_{\Omega} \int_0^T \frac{\partial u}{\partial t} u^- dt dx &= \frac{1}{2} \int_{\Omega} u^-(x, T)^2 dx > 0 \\ a \left( \int_{\Omega} |u|^q dx \right) \int_{\Omega} \int_0^T u \bar{u}^- dt dx &= a \left( \int_{\Omega} |u|^q dx \right) \|u^-\|_{H_0^1(0, T; L^2(\Omega))}^2 > 0 \\ b(l(u)) \int_{\Omega} \int_0^T u u^- dt dx &= b(l(u)) \|u^-\|_{L^2(0, T; L^2(\Omega))}^2 > 0 \end{aligned}$$

Thus

$$\int_{\Omega} \int_0^T f(x, u) u^- dt dx > 0$$

But

$$\int_0^T \int_{\Omega} f(x, u) u^- dt dx \leq 0$$

Hence we get  $u^- = 0$  it means  $u > 0$

**Theorem 2** Let assume that condition (C<sub>1</sub>), (C<sub>2</sub>), (C<sub>3</sub>) and (H<sub>2</sub>) hold Then problem (2) has at least one positive solution

**Proof** We use Galerkin method Let  $\{w_k\}_{k=1}^{\infty} \subseteq H_0^1(\Omega)$  is an orthogonal basis of  $H_0^1(\Omega)$  and an orthonormal basis of  $L^2(\Omega)$ . Fix now a positive integer  $m \in \mathbb{N}$  set

$$V_m = \text{span}\{w_1, \dots, w_m\}.$$

We note

$$u_m(t) = \sum_{k=1}^m d_m^k(t) w_k(x), \quad (8)$$

and  $u_{0n} \rightarrow u_0$  in  $H_0^1(\Omega)$  to be the solution of approximate problem

$$\int_{\Omega} u'_m w_k dx + a(\int_{\Omega} |u_m|^{q-1} dx) \int_{\Omega} u_m \dot{y} w_k dx + b(l(u_m)) \int_{\Omega} u_m w_k dx = \int_{\Omega} (x, u_m) w_k dx, \quad (9)$$

$$u_m(0) = u_{0n}, \quad u_m \in V_m. \quad (10)$$

According to stand existence theory for linear ordinary differential equations there (9) has a unique solution  $u_m$ . We now to show a subsequence of our solution  $(u_m)$  converges to a weak solution of problem (2). For this we will need some priori estimate Multiply (9) by  $d_m^k(t)$ , sum for  $k = 1, \dots, m$ . We can find

$$\int_{\Omega} u'_m u_m dx + a(\int_{\Omega} |u_m|^{q-1} dx) \int_{\Omega} u_m \dot{y} u_m dx + b(l(u_m)) \int_{\Omega} u_m^2 dx = \int_{\Omega} (x, u_m) u_m dx,$$

$0 \leq t \leq T$ . By using (H<sub>2</sub>) and Cauchy's inequality with  $\epsilon$  take  $\epsilon = 4a$ , we can get

$$\frac{d}{dt} (\|u_m\|_{L^2(\Omega)}^2) + 2m_0 \|u_m\|_{H_0^1(\Omega)}^2 \leq 2c \|u_m\|_{L^2(\Omega)}^2 + 2c^2 |\Omega|. \quad (11)$$

Hence

$$\frac{d}{dt} (\|u_m(t)\|_{L^2(\Omega)}^2) \leq 2c \|u_m\|_{L^2(\Omega)}^2 + 2c^2 |\Omega|.$$

By using Gronwall's inequality we have

$$\|u_m(t)\|_{L^2(\Omega)}^2 \leq C_1 (\|u_0\|_{L^2(\Omega)}^2 + 2c^2 |\Omega| T). \quad (12)$$

Integrate (11) from 0 to  $T$  and using (12) we obtain

$$\|u_m\|_{L^2(0,T;H_0^1(\Omega))}^2 + 2m_0 \|u_m\|_{L^2(0,T;H_0^1(\Omega))}^2 \leq C_2 (\|u_0\|_{L^2(\Omega)}^2 + 2c^2 |\Omega| T).$$

Hence

$$\|u_m\|_{L^2(0,T;H_0^1(\Omega))}^2 = \int_0^T \|u_m(t)\|_{H_0^1(\Omega)}^2 dt \leq C_3 (\|u_0\|_{L^2(\Omega)}^2 + 2c^2 |\Omega| T). \quad (13)$$

Fix any  $v \in H_0^1(\Omega)$  with  $\|v\|_h \leq 1$  and  $v = v^1 + v^2$ , where  $v^1 \in V^m$  and  $(v^2, w_k) = 0 (k = 1, \dots, m)$ , by (9) we get that

$$\int_{\Omega} \frac{du_m}{dt} v^1 dx + a(\int_{\Omega} |u_m|^{q-1} dx) \int_{\Omega} u_m \dot{y} v^1 dx + b(l(u_m)) \int_{\Omega} u_m v^1 dx = \int_{\Omega} (x, u_m) v^1 dx,$$

as  $0 \leq t \leq T$ , by (8) it follows that

$$\begin{aligned} \int_{\Omega} \frac{du_m}{dt} v dx &= \int_{\Omega} \frac{du_m}{dt} v^1 dx = \\ &\int_{\Omega} (x, u_m) v^1 dx - a(\int_{\Omega} |u_m|^{q-1} dx) \int_{\Omega} u_m \dot{y} v^1 dx - b(l(u_m)) \int_{\Omega} u_m v^1 dx. \end{aligned}$$

Consequently

$$|\langle u'_m, v \rangle| \leq C_3 (M \|u_m\|_{H_0^1(\Omega)} + (c |\Omega|^{\frac{1}{2}} + \beta) \|u_m\|_{L^2(\Omega)}) + c |\Omega|,$$

thus

$$\|u'_m\|_{H^{-1}} \leq C_3(M \|u_m\|_{H_0^1(\Omega)} + (c|\Omega|^{\frac{1}{2}} + \beta) \|u_m\|_{L^2(\Omega)}) + c|\Omega|, \quad (14)$$

since  $\|v\|_{H_0} \leq 1$ . Integrate (14) from 0 to  $T$  and (12) we obtain

$$\|u'_m\|_{L^2(0,T;H^{-1}(\Omega))} \leq C_4. \quad (15)$$

Next we pass to limit in (9) as  $m \rightarrow \infty$ . According to (13), (15), we see that the sequence  $\{u_m\}_{m=1}^\infty$  is bounded in  $L^2(0, T; H_0^1(\Omega))$  and  $\{u'_m\}_{m=1}^\infty$  is bounded in  $L^2(0, T; H^{-1}(\Omega))$ . We deduce the existence a subsequence of  $(u_m)$  such that

$$\begin{aligned} u_m &\rightharpoonup u \text{ in } L^2(0, T; H_0^1(\Omega)), \quad u'_m \rightharpoonup u' \text{ in } L^2(0, T; H^{-1}(\Omega)), \\ u_m &\rightarrow u \text{ in } L^2(0, T; L^p(\Omega)), \quad 1 \leq p < 2N/(N-2), \end{aligned}$$

passing to limit in (9) we get that

$$\int_{\Omega} u' w_k + a \left( \int_{\Omega} |u|^q dx \right) \int_{\Omega} u \bar{y} w_k dx + b(l(u)) \int_{\Omega} u w_k dx = \int_{\Omega} (x, u) w_k dx. \quad (16)$$

From the completeness of  $w_k$ , (16) holds with  $w_k$  replaced by any  $v \in H_0^1(\Omega)$ . Hence

$$\int_{\Omega} u' v dx + a \left( \int_{\Omega} |u|^q dx \right) \int_{\Omega} u \bar{y} v dx + b(l(u)) \int_{\Omega} u v dx = \int_{\Omega} (x, u) v dx.$$

By Lemma 1, it shows  $u$  is a positive solution

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